

TDA7385

4 x 22W FOUR BRIDGE CHANNELS CAR RADIO AMPLIFIER

ADVANCE DATA

- HIGH OUTPUT POWER CAPABILITY: 4 x 30W max./4Ω EIAJ 4 x 22W/4Ω @ 14.4V, 1KHz, 10% 4 x 18.5W/4Ω @ 13.2V, 1KHz, 10%
- **CLIPPING DETECTOR**
- LOW DISTORTION
- LOW OUTPUT NOISE
- ST-BY FUNCTION
- MUTE FUNCTION
- AUTOMUTE AT MIN. SUPPLY VOLTAGE DE-**TECTION**
- DIAGNOSTICS FACILITY FOR:
- CLIPPING
 - OUT TO GND SHORT
 - OUT TO V_S SHORT
 - THERMAL SHUTDOWN
- LOW EXTERNAL COMPONENT COUNT:
 - INTERNALLY FIXED GAIN (26dB)
 - NO EXTERNAL COMPENSATION

BLOCK AND APPLICATION DIAGRAM

- NO BOOTSTRAP CAPACITORS

PROTECTIONS:

■ OUTPUT SHORT CIRCUIT TO GND, TO Vs. ACROSS THE LOAD

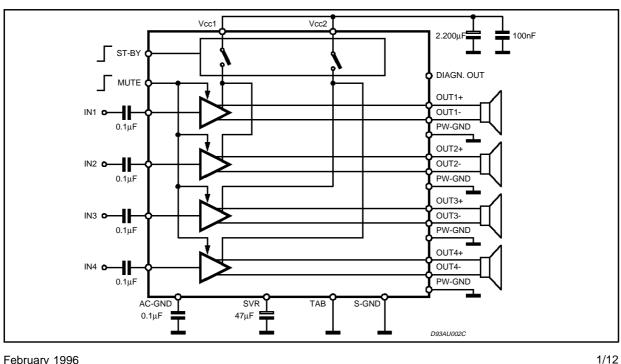
FLEXIWATT25

ORDERING NUMBER: TDA7385

- VERY INDUCTIVE LOADS
- OVERRATING CHIP TEMPERATURE WITH SOFT THERMAL LIMITER
- LOAD DUMP VOLTAGE
- FORTUITOUS OPEN GND
- REVERSED BATTERY
- ESD PROTECTION -

DESCRIPTION

The TDA7385 is a new technology class AB Audio Power Amplifier in Flexiwatt 25 package designed for high end car radio applications.



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This is advanced information on a new product now in development or undergoing evaluation. Details are subject to change without notice.

DESCRIPTION (continued)

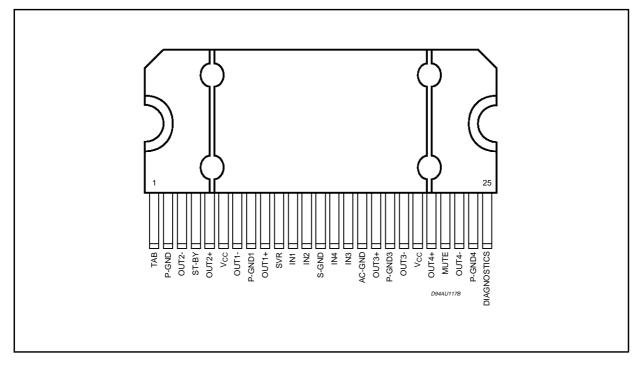
Thanks to the fully complementary PNP/NPN output configuration the TDA7385 allows a rail to rail output voltage swing with no need of bootstrap capacitors. The extremely reduced components count allows very compact sets.

The on-board clipping detector simplifies gain compression operations. The fault diagnostics makes it possible to detect mistakes during Car-Radio assembly and wiring in the car.

ABSOLUTE MAXIMUM RATINGS

Symbol	Parameter	Value	Unit
Vcc	Operating Supply Voltage	18	V
Vcc (DC)	DC Supply Voltage	28	V
V _{CC} (pk)	Peak Supply Voltage (t = 50ms)	50	V
Ι _Ο	Output Peak Current: Repetitive (Duty Cycle 10% at f = 10Hz) Non Repetitive (t = 100µs)	4.5 5.5	A A
P _{tot}	Power dissipation, $(T_{case} = 70^{\circ}C)$	80	W
Tj	Junction Temperature	150	°C
T _{stg}	Storage Temperature	– 55 to 150	°C

PIN CONNECTION (Top view)



THERMAL DATA

Symbol	Parameter	Value	Unit
R _{th j-case}	Thermal Resistance Junction to Case Max.	1	°C/W



Symbol	Parameter	Test Condition	Min.	Тур.	Max.	Unit
I _{q1}	Quiescent Current	iescent Current		180		mA
Vos	Output Offset Voltage				150	mV
Gv	Voltage Gain		25	26	27	dB
Po	Output Power	THD = 10% THD = 1%	18	22 18		W W
		$\begin{array}{l} \text{THD} = 10\%; \ \text{V}_{\text{S}} = 14\text{V} \\ \text{THD} = 5\%; \ \ \text{V}_{\text{S}} = 14\text{V} \\ \text{THD} = 1\%; \ \ \text{V}_{\text{S}} = 14\text{V} \end{array}$		21 19 17		W W W
		$\begin{array}{l} \text{THD} = 10\%; \ \text{V}_{\text{S}} = 13.2\text{V} \\ \text{THD} = 1\%; \ \ \text{V}_{\text{S}} = 13.2\text{V} \end{array}$		18.5 15		W W
P _{o max}	Max. Output Power	EIAJ RULES		30		W
THD	Distortion	$P_o = 4W$			0.3	%
e No	Output Noise	"A" Weighted Bw = 20Hz to 20KHz		50 65	150	μV μV
SVR	Supply Voltage Rejection	f = 100Hz	50	65		dB
fcl	Low Cut-Off Frequency			20		Hz
f _{ch}	High Cut-Off Frequency		75			KHz
Ri	Input Impedance		70	100		KΩ
Ст	Cross Talk	f = 1KHz	50	70		dB
I _{SB}	St-By Current Consumption	St-By = LOW			100	μA
V _{SBout}	St-By OUT Threshold Voltage	(Amp: ON)	3.5			V
V _{SB IN}	St-By IN Threshold Voltage	(Amp: OFF)			1.5	V
A _M	Mute Attenuation	V _O = 1Vrms		90		dB
V _{M out}	Mute OUT Threshold Voltage	(Amp: Play)	3.5			V
V _{M in}	Mute IN Threshold Voltage	(Amp: Mute)			1.5	V
I _{m (L)}	Muting Pin Current	V _{MUTE} = 1.5V (Source Current)	10	13	16	μA
I _{m (H)}	Muting Pin Current	VMUTE = 3.5V (Source Current)	6	10	14	μA
ICDOFF	Clipping Detector "OFF" Output Average Current	THD = 1% (*)		100		μA
ICDON	Clipping Detector "ON" Output Average Current	THD = 10% (*)		190		μA

ELECTRICAL CHARACTERISTICS (V_S = 14.4V; f = 1KHz; R_g = 600 Ω ; R_L = 4 Ω ; T_{amb} = 25°C; Refer to the Test and application circuit (fig.1), unless otherwise specified.)

(*) Diagnostics output pulled-up to 5V with 10K $\!\Omega$ series resistor.



TDA7385

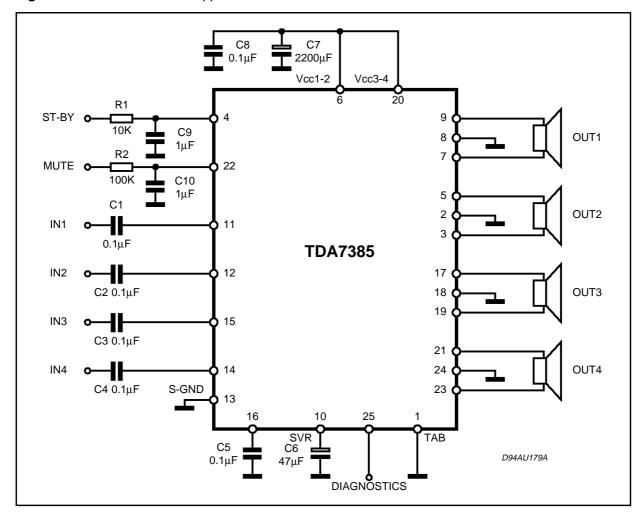


Figure 1: Standard Test and Application Circuit



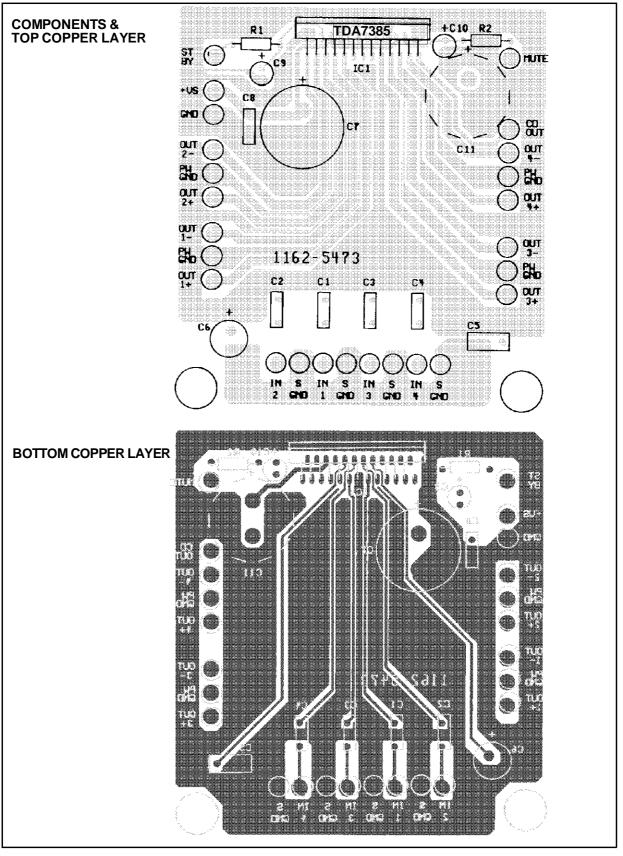


Figure 2: P.C.B. and component layout of the figure 1 (1:1 scale)



Po (W) 35

RL= 4 Ohm

10

g

f= 1 KHz

30

25

20

15

10

5× 8

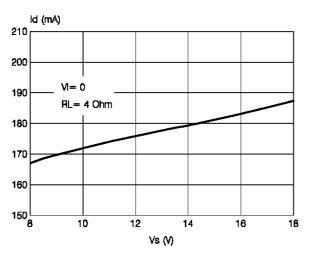


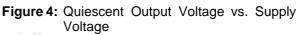
Figure 5: Output Power vs. Supply Voltage

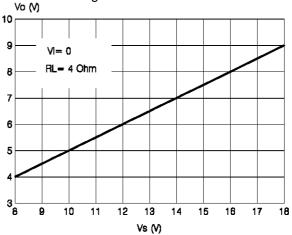
THD= 10 %

15 16 17 18

THD= 1 %

Figure 3: Quiescent Current vs. Supply Voltage







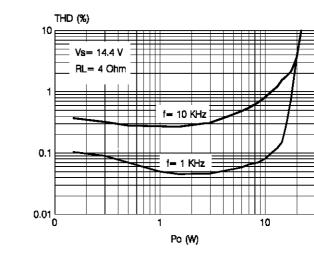


Figure 7: Distortion vs. Frequency.

11

12

13 14

Vs (V)

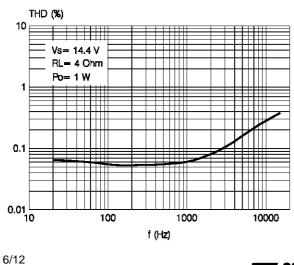


Figure 8: Supply Voltage Rejection vs. Frequency by varying C6

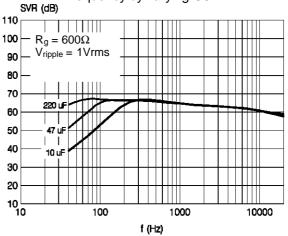
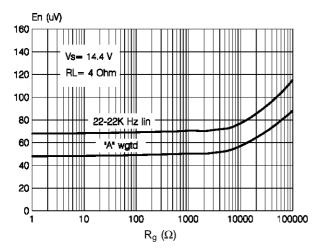






Figure 9: Output Noise vs. Source Resistance

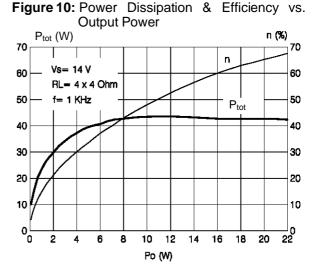


APPLICATION HINTS (ref. to the circuit of fig. 1) BIASING AND SVR

As shown by fig. 11, all the TDA7385's main sections, such as INPUTS, OUTPUTS AND AC-GND (pin 16) are internally biased at half Supply Voltage level (Vs/2), which is derived from the Supply Voltage Rejection (SVR) block. In this way no current flows through the internal feedback network.

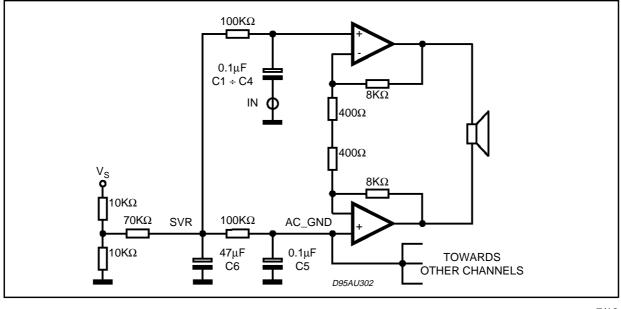
The AC-GND is common to all the 4 amplifiers and represents the connection point of all the inverting inputs.

Both individual inputs and AC-GND are connected to Vs/2 (SVR) by means of $100 \text{K}\Omega$ resistors.



To ensure proper operation and high supply voltage rejection, it is of fundamental importance to provide a good impedance matching between IN-PUTS and AC-GROUND terminations. This implies that C₁, C₂, C₃, C₄, C₅ CAPACITORS HAVE TO CARRY THE SAME NOMINAL VALUE AND THEIR TOLERANCE SHOULD NEVER EXCEED ± 10 %.

Besides its contribution to the ripple rejection, the SVR capacitor governs the turn ON/OFF time sequence and, consequently, plays an essential role in the pop optimization during ON/OFF transients. To conveniently serve both needs, **ITS MINIMUM RECOMMENDED VALUE IS 10\muF**.



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Figure 11: Input/Output Biasing.

INPUT STAGE

The TDA7385'S inputs are ground-compatible and can stand very high input signals (\pm 8Vpk) without any performances degradation.

If the standard value for the input capacitors (0.1 $\mu\text{F})$ is adopted, the low frequency cut-off will amount to 16 Hz.

STAND-BY AND MUTING

STAND-BY and MUTING facilities are both CMOS-COMPATIBLE. If unused, a straight connection to Vs of their respective pins would be admissible. Conventional low-power transistors can be employed to drive muting and stand-by pins in absence of true CMOS ports or microprocessors.

R-C cells have always to be used in order to smooth down the transitions for preventing any audible transient noises.

Since a DC current of about 10 uA normally flows out of pin 22, the recommended muting-series resistance (R₂) is in the range $70K\Omega$ to $120K\Omega$, which is also sufficiently high to allow a muting capacitor reasonably small (about 1µF).

If R_2 values higher than recommended are chosen, the involved risk will be that the voltage at pin 22 may rise to above the 1.5 V threshold voltage and the device will consequently fail to turn OFF when the mute line is brought down.

Conversely, in case of R_2 lower than 70K Ω , no negative impact will exist other than the necessity to increase C_{10} if the pop during muting operations grows to unacceptable levels.

About the stand-by, the time constant to be assigned in order to obtain a virtually pop-free transition has to be slower than 2.5V/ms.

DIAGNOSTICS FACILITY

The TDA7385 is equipped with a diagnostics circuitry able to detect the following events:

- CLIPPING in the output stage
- OVERHEATING (THERMAL SHUT-DOWN proximity)
- OUTPUT MISCONNECTIONS (OUT-GND & OUT-Vs shorts)

Diagnostics information is available across an open collector output located at pin 25 (fig. 12) through a current sinking whenever at least one of the above events is recognized.

Among them, the **CLIPPING DETECTOR** acts in a way to output a signal as soon as one or more power transistors start being saturated.

As a result, the clipping-related signal at pin 25 takes the form of pulses, which are perfectly syncronized with each single clipping event in the music program and reflect the same duration time (fig. 13). Applications making use of this facility usually operate a filtering/integration of the pulses train through passive R-C networks and realize a volume (or tone bass) stepping down in association with microprocessor-driven audioprocessors.

Figure 12: Diagnostics circuit.

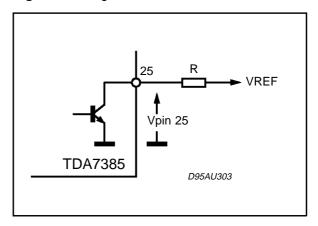
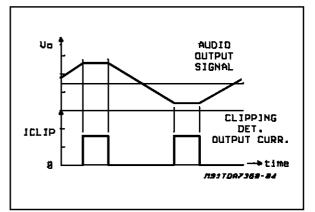


Figure 13: Clipping Detection Waveforms.



The maximum load that pin 25 can sustain is $1 K \Omega.$

Due to its operating principles, the clipping detector has to be viewed mainly as a power-dependent feature rather than frequency-dependent. This means that clipping state will be immediately signaled out whenever a fixed power level is reached, regardless of the audio frequency.

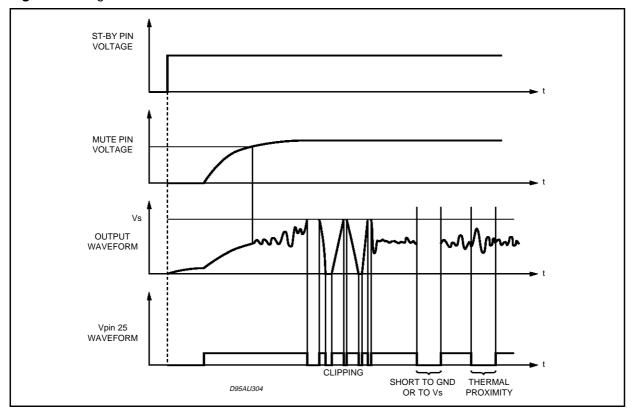
In other words, this feature offers the means to counteract the extremely sound-damaging effects of clipping, caused by a sudden increase of odd order harmonics and appearance of serious intermodulation phenomena.

Another possible kind of distortion control could be the setting of a maximum allowable THD limit (e.g. 0.5 %) over the entire audio frequency range. Besides offering no practical advantages, this procedure cannot be much accurate, as the non-clipping distortion is likely to vary over frequency.



8/12

Figure 14: Diagnostics Waveforms.

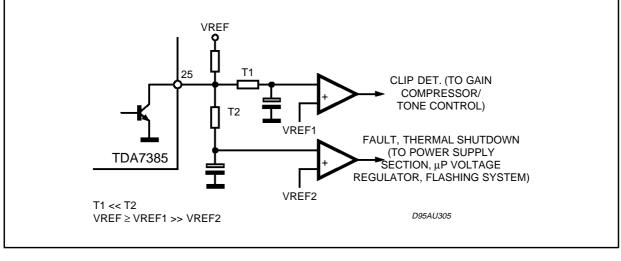


In case of **OVERHEATING**, pin 25 will signal out the junction temperature proximity to the thermal shut-down threshold. This will typically start about 2°C before the thermal shut-down threshold is reached.

As various kind of diagnostics information is available at pin 25 (CLIPPING, SHORTS AND OVER-HEATING), it may be necessary to operate some distinctions on order to treat each event separately. This could be achieved by taking into account the intrinsically different timing of the diagnostics output under each circumstance.

In fact, clipping will produce pulses normally much shorter than those present under faulty conditions. An example of circuit able to distinguish between the two occurrences is shown by fig. 15.

Figure 15.





STABILITY AND LAYOUT CONSIDERATIONS

If properly layouted and hooked to standard carradio speakers, the TDA7385 will be intrinsically stable with no need of external compensations such as output R-C cells. Due to the high number of channels involved, this translates into a very remarkable components saving if compared to similar devices on the market.

To simplify pc-board layout designs, each amplifier stage has its own power ground externally accessible (pins 2,8,18,24) and one supply voltage pin for each couple of them.

Even more important, this makes it possible to achieve the highest possible degree of separation among the channels, with remarkable benefits in terms of cross-talk and distortion features.

About the layout grounding, it is particularly important to connect the AC-GND capacitor (C_5) to the signal GND, as close as possible to the audio inputs ground: this will guarantee high rejection of any common mode spurious signals.

The SVR capacitor (C_6) has also to be connected to the signal GND.

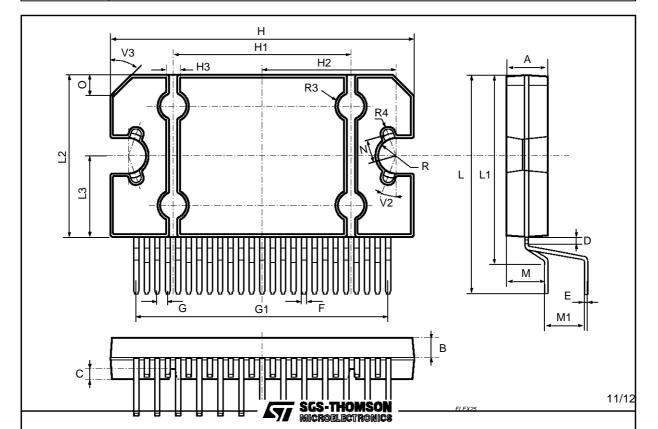
Supply filtering elements (C_7 , C_8) have naturally to be connected to the power-ground and located as close as possible to the Vs pins.

Pin 1, which is mechanically attached to the device's tab, needs to be tied to the cleanest power ground point in the pc-board, which is generally near the supply filtering capacitors.



DIM.	mm			inch			
	MIN.	TYP.	MAX.	MIN.	TYP.	MAX.	
А	4.45		4.65	0.175		0.183	
В	1.80	1.90	2.00	0.070	0.074	0.079	
С		1.40			0.055		
D	0.75	0.90	1.05	0.029	0.035	0.041	
E	0.37	0.39	0.42	0.014	0.015	0.016	
F			0.57			0.022	
G	0.80	1.00	1.20	0.031	0.040	0.047	
G1	23.75	24.00	24.25	0.935	0.945	0.955	
Н	28.90	29.23	29.30	1.138	1.150	1.153	
H1		17.00			0.669		
H2		12.80			0.503		
H3		0.80			0.031		
L	21.57	21.97	22.37	0.849	0.865	0.880	
L1	18.57	18.97	19.37	0.731	0.786	0.762	
L2	15.50	15.70	15.90	0.610	0.618	0.626	
L3	7.70	7.85	7.95	0.303	0.309	0.313	
М	3.70	4.00	4.30	0.145	0.157	0.169	
M1	3.60	4.00	4.40	0.142	0.157	0.173	
Ν		2.20			0.086		
0		2			0.079		
R		1.70			0.067		
R4		0.50			0.019		
V2	20°						
V3	45°						

FLEXIWATT25 PACKAGE MECHANICAL DATA



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